Controlling false discovery proportion in structured data sets

PhD defense, November 30 2023

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Multiplicity in scientific research



Neuroscience



Also in medicine for clinical trials, astrophysics...

Multiplicity : statistical formalism

• Observe $X \sim P$ (unknown)

X matrix of gene expression

- For i ∈ {1,...,m} test simultaneously null hypotheses H_{0,i}: "gene i is not related to cancer" vs H_{1,i}: "gene i is related to cancer"
- *P*-value based testing: each $H_{0,i}$ is represented by valid *p*-value $p_i(X) = p_i \in (0,1)$

A valid *p*-value verifies

 $\mathbb{P}_{X \sim P}(p \leq u) \leq u$, for all $u \in [0, 1]$, when P satisfies H_0

Multiple Testing (MT)

 \longrightarrow Goal: make interesting discoveries while limiting # errors

 $\begin{array}{c} {\cal H}_0 \ {\rm (unknown)} \\ {\rm contains \ true \ nulls} \ \ {\sf X} \end{array}$

 \mathcal{H}_1 (unknown) contains true alternatives ullet



- True discovery
- $\langle X \rangle$ False discovery

Uncorrected MT

 \longrightarrow Testing all $H_{0,i}$ at same level $\alpha \in (0,1)$

Individual Type I error controlled

 $\mathbb{P}(p_i(X) \leq \alpha) \leq \alpha$ for all $\alpha \in (0, 1)$, and $i \in \mathcal{H}_0$

Because *p*-values are valid

Overall nb errors in expectation explodes

Under global null, with $m \ge 1$ uniform *p*-values, $\mathbb{E}\left[\sum_{j=1}^{m} 1_{p_j \le \alpha}\right] = m\alpha$

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MT error metric

 $\label{eq:MT} \begin{array}{l} \mathsf{MT} \approx \texttt{[assessing overall quality]} \text{ of decisions taken} \\ \longrightarrow \mathsf{Notion of Type I error accounting for multiplicity} \end{array}$

False Discovery Proportion (FDP) [Benjamini and Hochberg, 1995]

 $\mathsf{FDP} = \frac{\#\mathsf{false \ discoveries}}{\#\mathsf{discoveries}}$

- Random quantity, thus either
 - \rightarrow control expectation : False Discovery Rate (FDR)
 - \longrightarrow control tail distribution : provide confidence bounds

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FDP related risks

FDR control : prescribe rejection set

Design procedure $R : [0,1]^m \to \mathcal{P}(\{1,\ldots,m\})$ s.t. for any $\alpha \in (0,1)$

$$\mathsf{FDR} := \mathbb{E}[\mathsf{FDP}(R)] \le \alpha$$

FDP confidence bounds : evaluate selection sets

For $R \in \mathcal{P}(\{1, \ldots, m\})$, provide upper bound $\overline{FDP}(R)$ s.t

 $\mathsf{P}(\mathsf{FDP}(R) \le \overline{\mathsf{FDP}}(R)) \ge 1 - \delta,$

for some $\delta \in (0, 1)$

Goal: control + power

→ few Type II error for FDR
 → sharpness for confidence bounds

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 \hookrightarrow few Type II error for FDR \hookrightarrow sharpness for confidence bounds

\longrightarrow Classical methods derived for "canonical setting"



"Structured" *p*-value ≈ when canonical feature not met
 → rethink/adapt the methods

• Structure defined upon availability, ordering, and marginal distribution

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Informal presentation



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Focus : combination of *p*-value structures + one MT goal

Chapter 2: Online multiple testing with super-uniformity reward → Online, discrete

 \longrightarrow Online mFDR control

Chapter 3: Consistent FDP bounds → Preordered (knockoff) *p*-values → Uniform FDP confidence bounds

Chapter 4: Unified class of π_0 estimators with plug-in FDR control \longrightarrow Discrete *p*-values

 \longrightarrow Adaptive FDR control

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- \longrightarrow Discrete *p*-values
- \longrightarrow Adaptive FDR control

Online multiple testing with super-uniformity reward Sebastian Döhler, Iqraa Meah, Etienne Roquain

[B] arXiv:2110.01255, in revision for EJS

Online multiple testing setting



 $\mathcal{F}_{t-1} = \sigma\left(1_{p_1 \leq lpha_1}, \dots, 1_{p_{t-1} \leq lpha_{t-1}}
ight)$ represents past

Assumption

 $\mathbb{P}\left(p_t \leq u \mid \mathcal{F}_{t-1}
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Online Multiple Testing (OMT) Formalism

 \rightarrow Goal: procedure with online mFDR $\leq \alpha$

Online error metric

For a procedure $\mathcal{A} = \{ \alpha_t, t \geq 1 \}$

$$\mathsf{mFDR}(\mathcal{A}) := \sup_{t \geq 1} rac{\mathbb{E}[|\mathcal{H}_0 \cap R(t)|]}{\mathbb{E}[1 \lor |R(t)|]}$$

 \mathcal{H}_0 set of true nulls $R(t) = \{1 \le i \le t : p_i \le \alpha_i\}$ rejection set up to time $t \ge 1$

• Tool : FDP estimation $FDP(t) = \frac{\sum_{j \le t, j \in \mathcal{H}_0} 1_{p_j \le \alpha_j}}{1 \vee |R(t)|} \approx \frac{\sum_{j \le t, j \in \mathcal{H}_0} \alpha_j}{1 \vee |R(t)|} \le \frac{\sum_{j \le t} \alpha_j}{1 \vee |R(t)|} := \widehat{FDP}(t)$

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OMT procedure

Lemma [Ramdas et al., 2017]

For $\mathcal{A} = \{\alpha_t, t \ge 1\}$ s.t. $\forall t \ge 1, \sum_{j \le t} \alpha_j \le \alpha(1 \lor |\mathcal{R}(t)|), \mathsf{mFDR}(\mathcal{A}) \le \alpha$

- Standard procedure : Level based On Recent Discoveries (LORD) [Javanmard and Montanari, 2018, Ramdas et al., 2017]
- Baseline strategy: Generalized α -investing (GAI) [Foster and Stine, 2008] $\hookrightarrow \alpha$ wealth to pay errors



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Super-uniformity

Classical setting

Adaptivity [Ramdas et al., 2018] Asynchronous setting [Zrnic et al., 2021] Power study [Chen and Arias-Castro, 2021]

One p-value at a time Uniform under the null $rac{1}{\tau_{1}}$ $rac{1}{\tau_{1}}$ $rac{1}{\tau_{1}}$ $rac{1}{\tau_{1}}$ $rac{1}{\tau_{1}}$ $rac{1}{\tau_{1}}$





Super-uniformity



$$F_t(u) = \mathbb{P}\left(p_t \leq u \mid \mathcal{F}_{t-1}\right) \leq u$$

a.s. for all
$$u \in [0,1]$$
, with $t \in \mathcal{H}_0$

 $\begin{array}{l} \mbox{Equality} \rightarrow \mbox{Uniform} \\ \mbox{Strict inequality} \rightarrow \mbox{over-conservativeness} \end{array}$

$$F_t(\alpha_t) := \mathbb{P}(p_t \le \alpha_t \mid \mathcal{F}_{t-1}) \le \underbrace{\tilde{\alpha}_t < \alpha_t}_{\text{over-conservativeness}}$$

 \longrightarrow Could be coped with F_t if known \hookrightarrow Typical case of discrete *p*-values : $\rho_t = \alpha_t - F_t(\alpha_t)$ explicit

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Discrete *p*-values



- Fisher Exact Tests (FETs) for association studies
 - $\hookrightarrow X$: gene knocked out or not
 - Y: change phenotype or not

	Y = 1	Y = 0	Total
<i>X</i> = 0	<i>n</i> ₁₁	<i>n</i> ₁₂	<i>n</i> ₁ .
X = 1	n ₂₁	n ₂₂	n ₂ .
Total	n.1	n.2	n

• Also Poisson, Binomial tests...

Contribution

Super-uniformity reward

 \longrightarrow Re-incorporate $\rho_t = \alpha_t - F_t(\alpha_t)$ as reward

Theorem [Döhler, M. and Roquain (2021)]

For any procedure $\mathcal{A}^0=(lpha_t^0,t\geq 1)$ satisfying almost surely, for all $t\geq 1$,

 $\sum_{1 \leq j \leq t} \alpha_j^0 \leq \alpha \ (1 \lor R(t)),$

the rewarded procedure $\mathcal{A} = (\alpha_t, t \geq 1)$ defined by

$$\alpha_t = \alpha_t^{\mathbf{0}} + \sum_{1 \le j \le t-1} \gamma'_{t-j} (\alpha_j - F_j(\alpha_j))$$

with $\gamma' = (\gamma'_t)_{t \ge 1}$ sequence of non-negative values summing to one

controls online mFDR at level α under conditional validity
 uniformly dominates the base procedure A⁰

Proof intuition : $\widehat{\text{FDP}}(t) = \frac{\sum_{j \le t} F_j(\alpha_j)}{1 \lor |R(t)|} \le \frac{\sum_{j \le t} \alpha_j}{1 \lor |R(t)|}$ tighter estimate

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International Mice Phenotyping Consortium (IMPC) dataset
 → Study genotype effect on phenotype
 Is gene X related to eye color ?

 → In vivo study with gene knockout

- Benchmark dataset analyzed in online literature
- Analyzed using FETs

mFDR procedures	LORD	hoLORD	ALORD	hoALORD
<pre># discoveries (male)</pre>	882	972	972	1041
<pre># discoveries (female)</pre>	839	946	966	1046

Extensions

- Online *p*-value weighting using rewarding method
- Control online mFDR at stopping times
- FDR control by enforcing monotonous reward across time

Perspectives

- Power study
 - ightarrow Optimal smoothing sequence $(\gamma_t')_{t\geq 1}$
 - ightarrow Super-uniformity reward optimal for $\sum_{j \leq t} F_j(lpha_j) \leq lpha(1 ee |R(t)|)$?

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Consistent false discovery proportion bounds Gilles Blanchard, Iqraa Meah, Etienne Roquain

[] arXiv:2306.07819, submitted

FDP confidence bounds

Quick background

Aim recall

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Confidence bounds on a path [Katsevich and Ramdas, 2020] Design bounding function $\overline{\text{FDP}}$ valued in (0, 1) s.t $P(\forall R_k \in \Pi, \text{FDP}(R_k) \leq \overline{\text{FDP}}(R_k)) \geq 1 - \delta,$ for some $\delta \in (0, 1)$

 $\Pi = path \rightarrow underlying setting: Top-k, Pre-ordered, Online$

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For $R_{\hat{k}_{\alpha}}$ output of FDR procedure at level α , $\overline{\text{FDP}}(R_{\hat{k}_{\alpha}}) \approx \alpha$?

Consistency for couple (FDR procedure, FDP bound) Formalism

Consistency [Blanchard, M. and Roquain (2023)]

 $orall\epsilon > 0, \ orall lpha_0 \in (0,1),$

$$\lim_{m\to\infty}\mathbb{P}^{(m)}\left(\sup_{\alpha\in[\alpha_0,1)}\left\{\overline{\mathsf{FDP}}_{\alpha}-\alpha\right\}\geq\epsilon\right)=0.$$

with $\overline{\text{FDP}}_{\alpha} = \overline{\text{FDP}}(R_{\hat{k}_{\alpha}})$ where $R_{\hat{k}_{\alpha}}$ output of FDR procedure at level α , and $\mathbb{P}^{(m)}$ sequence of standard models

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 \hookrightarrow Today focus on (Knockoff, FDP bound)

Pre-ordered path : $R_k = \{\pi(i) : 1 \le i \le k, \ p_{\pi(i)} \le s\} \mid \frac{1}{2} \frac{9}{11} \frac{6}{5} \frac{1}{2} \frac{9}{11} \frac{1}{5} \frac{9}{11} \frac{1}{5} \frac{1}{5} \frac{9}{11} \frac{1}{5} \frac{1}{5} \frac{9}{11} \frac{1}{5} \frac{1}$ $\hookrightarrow s \in (0, 1]$ signal zone threshold



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$$\begin{split} \widehat{\mathsf{FDP}}(R_k) &= \widehat{\mathsf{FDP}}_k = \frac{s}{1-\lambda} \frac{1 + \sum_{i=1}^k 1\{p_{\pi(i)} > \lambda\}}{1 \vee \sum_{i=1}^k 1\{p_{\pi(i)} \le s\}} \quad \text{[Lei and Fithian, 2016]} \\ &\hookrightarrow \lambda \in (0, 1] \text{ error zone threshold} \end{split}$$

FDR procedure look for largest \hat{k}_{α} such that $\widehat{\mathsf{FDP}}_{\hat{k}_{\alpha}} \leq \alpha$

Encompasses [Barber and Candès, 2015] Knockoff procedure binary p-values and $\lambda = s = 1/2$

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Proposed bounds

KR bound [Katsevich and Ramdas, 2020]

$$\overline{\mathsf{FDP}}_{k}^{\mathsf{KR}} = 1 \land \left(\frac{\log(1/\delta)}{a\log(1 + \frac{1-\delta^{B/a}}{B})} \frac{a + \frac{s}{1-\lambda} \sum_{i=1}^{k} \mathbb{1}\{p_{\pi(i)} > \lambda\}}{1 \lor \sum_{i=1}^{k} \mathbb{1}\{p_{\pi(i)} \le s\}} \right)$$

with $a \geq 1$ free parameter, $B = s/(1 - \lambda)$, and $\lambda \geq s$.

Default choice a = 1 suggested by KR.

KR-U bound (new) [Blanchard, M. and Roquain (2023)]

$$\overline{\mathsf{FDP}}_k^{\mathsf{KR}-\mathsf{U}} = 1 \wedge \min_{a \in \mathbb{N} \setminus \{0\}} \left\{ \frac{\log(1/\delta_a)}{a\log(1 + \frac{1-\delta_a^{B/a}}{B})} \frac{a + \frac{s}{1-\lambda} \sum_{i=1}^k \mathbb{1}\{p_{\pi(i)} > \lambda\}}{1 \vee \sum_{i=1}^k \mathbb{1}\{p_{\pi(i)} \leq s\}} \right\},$$

with $\delta_a = \delta/(\kappa a^2)$, $a \ge 1$, for $B = s/(1 - \lambda)$, $\kappa = \pi^2/6$.

 \rightarrow Our proposal : KR + union bound over $a \in \mathbb{N} \setminus \{0\}$

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 $\overline{\mathsf{FDP}}_{\alpha} = \overline{\mathsf{FDP}}(R_{\hat{k}_{\alpha}}) \text{ with } R_{\hat{k}_{\alpha}} \text{ output of Knockoff at level } \alpha \in (0,1)$ $\hookrightarrow \overline{\mathsf{FDP}}(R_{\hat{k}_{\alpha}}) = \mathsf{factor} \cdot \alpha + \mathsf{remainder}/\hat{r}_{\alpha}, \text{ with } \hat{r}_{\alpha} = \# \text{ rejections}$

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$$\overline{\mathsf{FDP}}^{\mathsf{KR}}_{\alpha} = 1 \land \left(\frac{\log(1/\delta)}{\log(1 + \frac{1 - \delta^B}{B})} \left(\alpha + 1/(1 \lor \hat{r}_{\alpha}) \right) \right)$$

 \hookrightarrow Incompressible constant o no consistency

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Illustration

[Lei and Fithian, 2016] VCT model

- Local alternative π(i) = 1/2 + (0 ∨ 1/2(^{z-i}/_{z-1})),

 → z > 1 tells how slowly probability of observing signal deteriorates
- Binary *p*-values : Under the null $p_i = 1/2$ or 1 with equal probability. Under the alternative, $p_i = 1/2$ with probability 0.9 and $p_i = 1$ otherwise.



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Other covered settings:

- top-k: consistency for (BH, FDP bounds) Uniform improvement by π₀-estimation
- online : consistency for (LORD, FDP bounds)

A unifying class of $\pi_{\rm 0}$ estimators with plug-in FDR control Sebastian Döhler, Iqraa Meah

arXiv:2307.13557, In revision for Biometrical Journal

Unifying class of π_0 estimators with plug-in FDR control

 $m_0 = |\mathcal{H}_0| \; \#$ true nulls $\pi_0 = \frac{m_0}{m}$ proportion of true nulls

 $\begin{aligned} \mathsf{FDR}(\mathsf{BH}_{\alpha}) &= \pi_0 \alpha \ll \alpha \text{ if dense signal} \\ \mathsf{FDR}(\mathsf{BH}_{\alpha/\pi_0}) &= \alpha \text{ nice but } \pi_0 \text{ unknown} \\ \mathsf{FDR}(\mathsf{BH}_{\alpha/\hat{\pi}_0}) &\leq \alpha \\ &\hookrightarrow \text{ sufficient condition for plug-in FDR control}: \quad [Benjamini et al., 2006] \end{aligned}$

[Blanchard and Roquain, 2009] (BR)



Contribution: general class of estimators verifying (BR) condition

- \hookrightarrow encompasses existing + new estimators
- \hookrightarrow allows adaptation to discreteness

Perspective : discrete BH with discrete (BR) condition

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Conclusion

General perspectives :

• Power studies

For optimal parameters \hookrightarrow challenging in online and discrete setting

• Relax independence

E-value based testing \rightarrow discrete E-values ?

Thank you for your attention !



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Online *p*-value weighting

P-value weighting : ease rejection when confident

Test on
$$\tilde{p}_t = p_t / (w_t) \rightarrow \text{prior knowledge}$$

 $\Leftrightarrow \text{Test } p_t \text{ with } \alpha_t w_t$

Well studied offline $\rightarrow (w_t)_{1 \le t \le m}$ unit mean, not obvious online Only solution [Ramdas et al., 2017] \rightarrow no rescaling (called wGAI)



 w_t inflates current investment if confident in rejection

 \rightarrow preserve wealth but less rejection reward to keep mFDR control

Online *p*-value weighting using super-uniformity

[Döhler, M. and Roquain (2021)]

Idea: enforce super-uniformity with $w_t \in (0,1)$

- \hookrightarrow Use only part of α_t if no confidence in rejection
- \rightarrow re-incorporate what was not used





mFDR procedures	LORD	wGAI	wLORD (new)
# discoveries	3550	1308	3875

Proof of concept on "airway" data set, with weights taken from

Monotonicity of online procedure

 α_t is a coordinate-wise nondecreasing function of past decisions:

Monotonicity if $\tilde{R}_i \ge R_i$ for all $i \le t - 1$, then we have $\alpha_t(\tilde{R}_1, \dots, \tilde{R}_{t-1}) \ge \alpha_t(R_1, \dots, R_{t-1})$

Rewarded procedures non monotone

Enforce monotonicity : look for "least favorable" super-uniformity reward over all possible past rejection sequences \rightarrow intractable

Estimator $\widehat{\text{FDP}}$ with adaptivity

Estimator FDP with adaptivity

$$\widehat{\mathsf{FDP}}_{\lambda}(T,\mathcal{A}) = \frac{\alpha_T + \sum_{\substack{1 \le t \le T-1, \\ p_t \ge \lambda}} F_t(\alpha_t)}{(1-\lambda)(1 \lor R(T))},$$

with $\lambda \in [0,1)$

 \rightarrow Intuition: count only for $p\mbox{-values}$ above λ because these are potentially true nulls

Stopping time control for rewarded procedures

Define the stopping time τ as any r.v taking values in $\{1,2,\dots\}$ with

- $\tau < +\infty$ almost surely;
- $\{\tau = t\} \in \mathcal{F}_t$ for all $t \ge 1$.

Stopping time control

Consider a stopping time τ as above. For any procedure $\mathcal{A} = (\alpha_t, t \ge 1)$, if for some $\lambda \in [0, 1)$ we have $\sup_{T>1} \widehat{\mathsf{FDP}}_{\lambda}(\mathcal{A}) \le \alpha$ then $\mathsf{mFDR}_{\tau}(\mathcal{A}) \le \alpha$.

 \rightarrow Proof:

$$M_{t} = \sum_{i \leq t, i \in \mathcal{H}_{0}} \left(1\left\{ p_{i} \leq \alpha_{i} \right\} - \frac{1\left\{ p_{i} > \lambda \right\}}{1 - \lambda} F_{i}\left(\alpha_{i}\right) \right), \quad t \geq 1$$

is a super-martingale.

Online Bonferroni

$$\alpha_t = \alpha \gamma_t \quad \forall t \ge 1$$

with $\{\gamma_t\}_{t\geq 1}$ a nonnegative sequence summing to one

- Controls online FWER \Rightarrow controls online mFDR
- α_t decrease quickly \rightarrow low power, no discoveries in long run
- Idea : scale budget by # rejections

Level based On Recent Discoveries (LORD) [Javanmard and Montanari, 2018, Ramdas et al., 2017]

$$\alpha_t = W_0 \gamma_t + (\alpha - W_0) \gamma_{t-\tau_1} + \alpha \sum_{j \ge 2} \gamma_{t-\tau_j} \quad \forall t \ge 1$$

with $W_0 \in [0, \alpha]$ an initial wealth, and τ_j time of the j^{th} discovery

Spending procedure for FWER control

 $\alpha_1 = \alpha \gamma_1$ $\alpha_2 = \alpha \gamma_2$ $\alpha_3 = \alpha \gamma_3$ \vdots

Investing procedures for mFDR control

$$\begin{aligned} \alpha_1 &= W_0 \gamma_1 \\ \alpha_2 &= W_0 \gamma_2 \quad \text{rejection} \\ \alpha_3 &= W_0 \gamma_3 + (\alpha - W_0) \gamma_1 \\ \alpha_4 &= W_0 \gamma_4 + (\alpha - W_0) \gamma_2 \quad \text{rejection} \\ \alpha_5 &= W_0 \gamma_5 + (\alpha - W_0) \gamma_3 + \alpha \gamma_1 \\ \vdots \end{aligned}$$

• Fisher Exact Tests (FETs) for association studies

 $\hookrightarrow X$: gene knocked out or not

Y: change phenotype or not

	Y = 1	Y = 0	Total
X = 0	n ₁₁	<i>n</i> ₁₂	<i>n</i> ₁ .
X = 1	n ₂₁	<i>n</i> ₂₂	n ₂ .
Total	n.1	n.2	n

Discreteness level



Discreteness level



Numerical results on simulated data Signal strength



Signal position



Discrete *p*-values Permutation test

• Permutation tests

$$egin{aligned} p(X) &= (B+1)^{-1} \left(1 + \sum_{b=1}^B \mathbbm{1} \left\{ S\left(X^{\sigma_b}
ight) \geq S(X)
ight\}
ight) \ &\mathbb{P}(p(X) \leq s) \leq F(s) = rac{\lfloor (B+1)s
floor}{B+1} \end{aligned}$$



Unifying class of π_0 estimators with plug-in FDR control $_{\rm Bias\ inflation}$

$$\mathsf{Bias}(\hat{m}_0^{\mathsf{Storey}}) = \frac{1}{1-\lambda} + \frac{1}{1-\lambda} \left(\sum_{i \in \mathcal{H}_0} \mathbb{E}[1_{\rho_i > \lambda}] + \sum_{i \in \mathcal{H}_1} \mathbb{E}[1_{\rho_i > \lambda}] \right) - m_0$$

• Under Uniform setting

$$rac{1}{1-\lambda} + rac{1}{1-\lambda} \left(\sum_{i \in \mathcal{H}_1} \mathbb{E}[\mathbf{1}_{
ho_i > \lambda}]
ight)$$

• Under Discrete setting

$$\frac{1}{1-\lambda} + \frac{1}{1-\lambda} \left(\sum_{i \in \mathcal{H}_0} 1 - F_i(\lambda) + \sum_{i \in \mathcal{H}_1} \mathbb{E}[1_{\rho_i > \lambda}] \right) - m_0$$